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Energy-based Models --Boltzmann Machine

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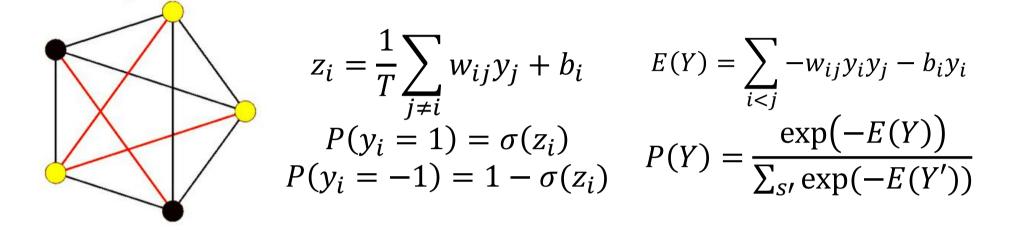
Content

- Boltzmann Machine
 - Introduction
 - Training without hidden neurons
 - Training with hidden neurons
 - Summary
- Restricted Boltzmann Machine
- Deep Boltzmann Machine



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- The stochastic Hopfield net models a probability distribution over states
 - The state Y is a binary sequence
 - It models a Boltzmann distribution
- The probability that the network will be in any state is P(Y)
 - Generative model: generates states according to P(Y)



- $P(Y) = P(y_i = 1 | y_{j \neq i}) P(y_{j \neq i})$
- Consider two states Y and Y' with the i-th bit in the +1 and -1

•
$$\log P(Y) - \log P(Y') = \log P(y_i = 1 | y_{j \neq i}) - \log P(y_i = -1 | y_{j \neq i})$$

= $\log \frac{P(y_i = 1 | y_{j \neq i})}{1 - P(y_i = 1 | y_{j \neq i})}$



• Consider two states Y and Y' with the i-th bit in the +1 and -1 $P(Y) = \frac{\exp(-E(Y))}{\sum_{s'} \exp(-E(Y'))}$

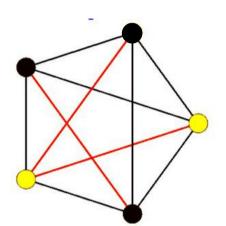
•
$$\log P(Y) = -E(Y) + C$$

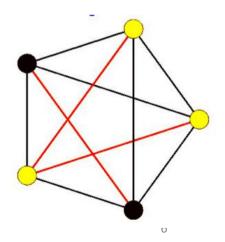
•
$$E(Y) = -\frac{1}{2}(E_{without i} + \sum_{j \neq i} w_{ij}y_j + b_i)$$

•
$$E(Y') = -\frac{1}{2}(E_{without i} - \sum_{j \neq i} w_{ij} y_j - b_i)$$

•
$$\log P(Y) - \log P(Y') = E(Y') - E(Y)$$

= $\sum_{j \neq i} w_{ij} y_j + b_i$





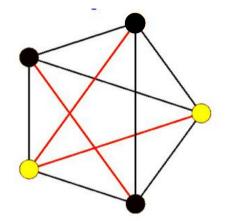
•
$$\log \frac{P(y_i = 1 | y_{j \neq i})}{1 - P(y_i = 1 | y_{j \neq i})} = \sum_{j \neq i} w_{ij} y_j + b_i$$

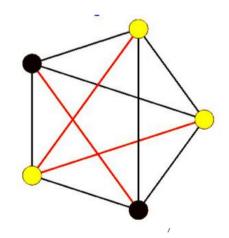
• We get:

•
$$P(y_i = 1 | y_{j \neq i}) = \frac{1}{1 + e^{-(\sum_{j \neq i} w_{ij}s_j + b_i)}}$$

• It's a logistic!

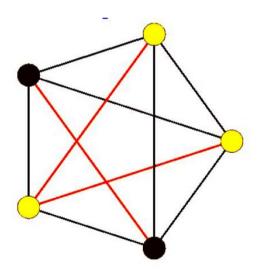








- We can make Hopfield net stochastic
 - Each neuron responds probabilistically
 - More in accord with Thermodynamic models
 - More likely to escape spurious "weak" memories

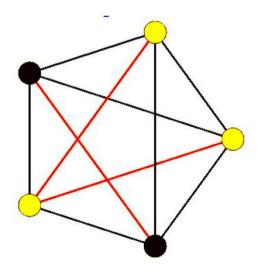


$$z_i = \frac{1}{T} \sum_{j \neq i} w_{ij} y_j + b_i$$
$$P(y_i = 1) = \sigma(z_i)$$
$$P(y_i = -1) = 1 - \sigma(z_i)$$



Running the network

- Initialise the neurons
- Cycle through the neurons and set the neurons to 1/-1 according to the probability
- Until convergence, sample the individual neurons



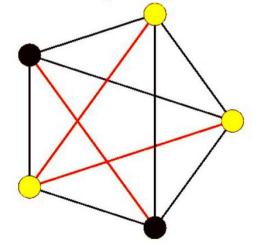
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$$P(y_i = -1) = 1 - \sigma(z_i)$$



The overall probability

- The probability of any state y can be shown to be given by the Boltzmann ulletdistribution

 - $E(y) = -\frac{1}{2}y^T W y$ $P(y) = Cexp(-\frac{E(y)}{T})$
- Minimising energy maximises log likelihood •
- The parameter of the distribution is the weights matrix W •

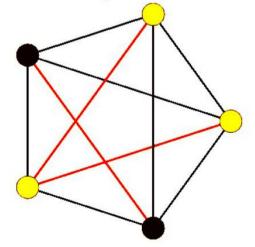


$$z_{i} = \frac{1}{T} \sum_{j \neq i} w_{ij} y_{j} + b_{i}$$
$$P(y_{i} = 1 | y_{j \neq i}) = \sigma(z_{i})$$
$$P(y_{i} = -1 | y_{j \neq i}) = 1 - \sigma(z_{i})$$



The overall probability

- The probability of any state y can be shown to be given by the Boltzmann ulletdistribution
 - $E(y) = -\frac{1}{2}y^T W y$ $P(y) = Cexp(-\frac{E(y)}{T})$
- The conditional distribution of individual bits in the sequence is a logistic ullet
- We call this Boltzmann Machine •



$$z_{i} = \frac{1}{T} \sum_{j \neq i} w_{ij} y_{j} + b_{i}$$
$$P(y_{i} = 1 | y_{j \neq i}) = \sigma(z_{i})$$
$$P(y_{i} = -1 | y_{j \neq i}) = 1 - \sigma(z_{i})$$

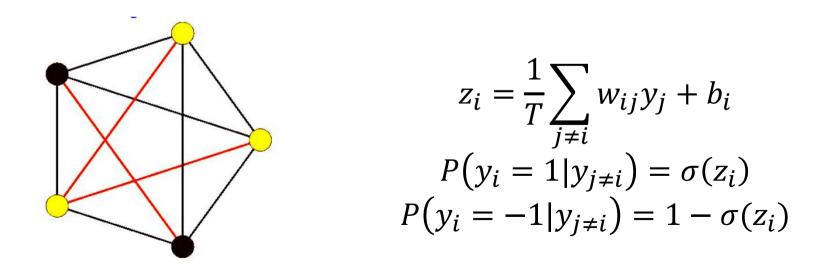
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Boltzmann Machine

- It can be viewed as a generative model
- Probability of producing any binary vector y:
 - $E(y) = -\frac{1}{2}y^T W y$

•
$$P(y) = Cexp(-\frac{E(y)}{T})$$

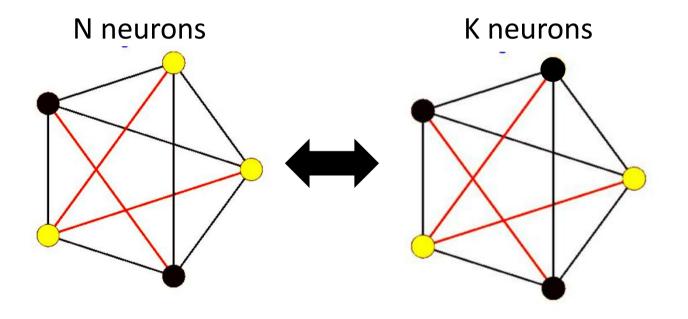


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The capacity of Boltzmann Machine



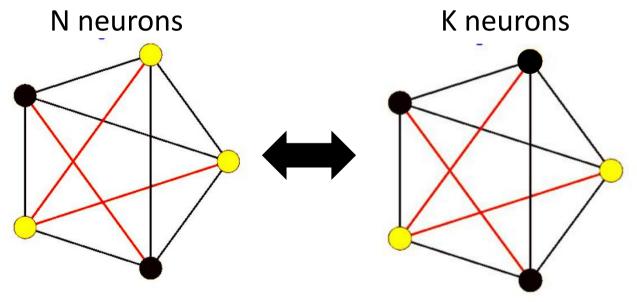
- The network can store up to N N-bit patterns
- How to increase the capacity?





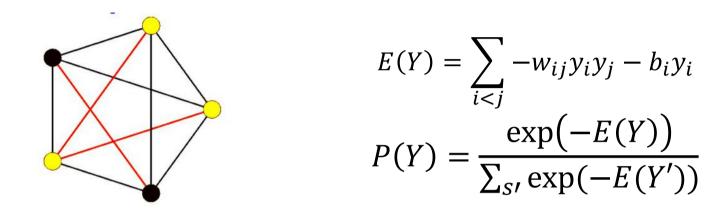
The capacity of Boltzmann Machine

- Add some nodes
 - We don't care the value of these nodes
 - Only serve to increase the capacity
 - Termed Hidden Neurons
- The neurons whose values are important: Visible Neurons





Hopfield Net v.s. Boltzmann machine



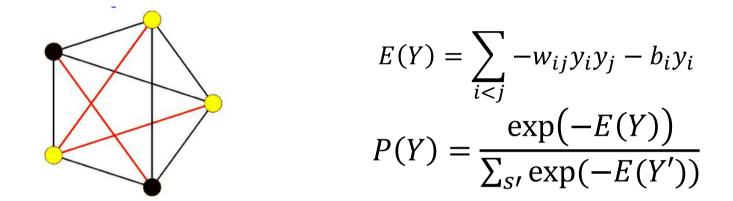
- Hopfield net
 - Learn weights to "remember" target states and "dislike" other states
 - State: binary pattern of all the neurons
- Boltzmann machine
 - Learn weights to assign more probability to patterns we "like" and less to other patterns



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- First we consider the setting without hidden neurons
- Boltzmann machine
 - Given a set of training inputs Y_1, Y_2, \dots, Y_N
 - Assign higher probability to patterns seen more frequently
 - Assign lower probability to patterns that are not seen at all



$$\log(P(Y)) = \left(\sum_{i < j} w_{ij} y_i y_j\right) - \log\left(\sum_{Y'} \exp\left(\sum_{i < j} w_{ij} y_i' y_j'\right)\right)$$
$$\mathcal{L} = \frac{1}{N} \sum_{Y \in S} \log(P(Y))$$
$$= \frac{1}{N} \sum_{Y} \left(\sum_{i < j} w_{ij} y_i y_j\right) - \log\left(\sum_{Y'} \exp\left(\sum_{i < j} w_{ij} y_i' y_j'\right)\right)$$

- The loss function is average log likelihood of training vectors $S = \{Y_1, Y_2, \dots, Y_N\}$
 - should be maximised
 - In the first summation, y_i and y_j are bits of Y
 - In the second summation, , y'_i and y'_j are bits of Y' (vectors outside S)



$$\mathcal{L} = \frac{1}{N} \sum_{Y} \left(\sum_{i < j} w_{ij} y_i y_j \right) - \log \left(\sum_{Y'} \exp \left(\sum_{i < j} w_{ij} y'_i y'_j \right) \right)$$
$$\frac{d\mathcal{L}}{dw_{ij}} = \frac{1}{N} \sum_{Y} y_i y_j -?$$

- Use gradient ascent
- The first term is easy to calculate
 - The average $y_i y_j$ over all training vectors
- But the second term is the sum of almost all states
 - exponential number!



The second term

$$\frac{d \log(\sum_{Y'} \exp(\sum_{i < j} w_{ij} y'_i y'_j))}{d w_{ij}} = \sum_{Y'} \frac{\exp(\sum_{i < j} w_{ij} y'_i y'_j)}{\sum_{Y''} \exp(\sum_{i < j} w_{ij} y''_i y''_j)} y'_i y'_j$$
$$= \sum_{Y'} P(Y') y'_i y'_j$$

- The second term is the expected value of y'_i, y'_j over all possible values of the state
- We cannot compute it exhaustively, then how?
- Sampling!



The second term

$$\frac{d \log(\sum_{Y'} \exp(\sum_{i < j} w_{ij} y'_i y'_j))}{d w_{ij}} = \sum_{Y'} P(Y') y'_i y'_j$$
$$= \frac{1}{M} \sum_{Y' \in Y_{sample}} y'_i y'_j$$

- The expectation can be estimated as the average of samples drawn from the distribution
- How to sample?



Gibbs Sampling

- A special Metropolis-Hastings algorithm
- Use the conditional distribution
- Suppose $y_1, y_2, ..., y_n$:
 - Randomly set values to them
 - Update y_i based on $P(y_i|y_{j\neq i})$
 - Get a Markov Chain
 - Skip the first several samples and sample at intervals
- The samples are approximately close to the joint distribution

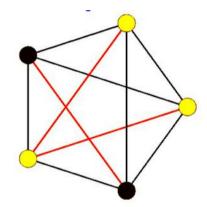


$$\frac{d\mathcal{L}}{dw_{ij}} = \frac{1}{N} \sum_{Y} y_i y_j - \frac{1}{M} \sum_{Y' \in Y_{sample}} y'_i y'_j$$
$$w_{ij} = w_{ij} + \alpha \frac{d\mathcal{L}}{dw_{ij}}$$

• The overall gradient ascent rule



Training Process

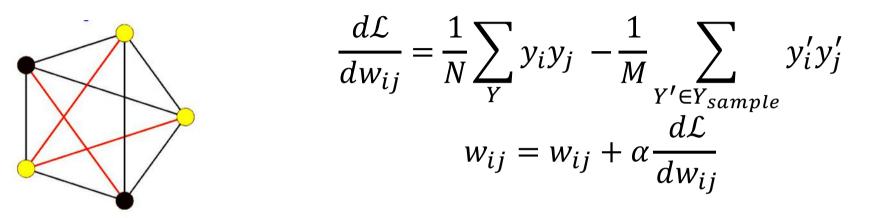


$$\frac{d\mathcal{L}}{dw_{ij}} = \frac{1}{N} \sum_{Y} y_i y_j - \frac{1}{M} \sum_{Y' \in Y_{sample}} y'_i y'_j$$
$$w_{ij} = w_{ij} + \alpha \frac{d\mathcal{L}}{dw_{ij}}$$

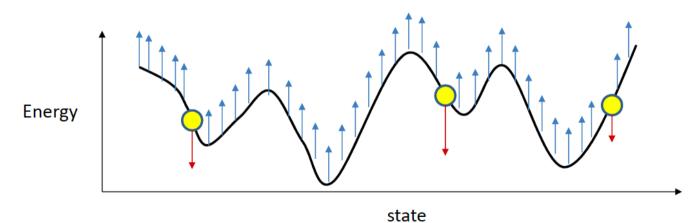
- Initialise weights
- Obtain "state samples"
- Compute gradient and update weights
- Iterate until convergence



Training Process



• Similar to the update rule for Hopfield network



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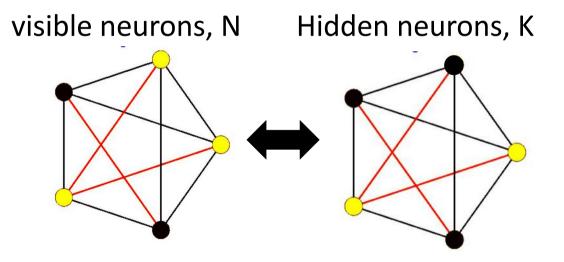
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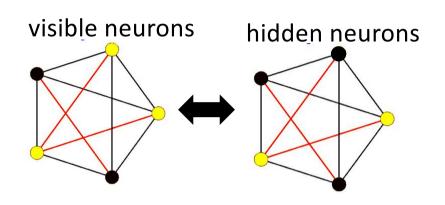
Training with hidden neurons



- For a given pattern of visible neurons, there are many hidden patterns (2^K)
- We want to choose the one with lowest energy
 - But exponential search space is exponential!



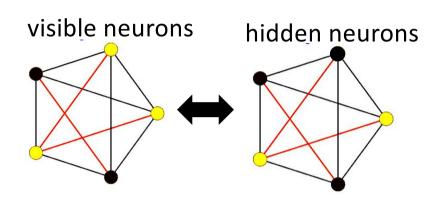
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$$P(Y) = \frac{\exp(-E(Y))}{\sum_{s'} \exp(-E(Y'))}$$
$$P(Y) = P(V, H)$$
$$P(V) = \sum_{H} P(Y)$$

- Y=(V, H)
 - V: output of the visible neurons
 - H: output of the hidden neurons
- The marginal probabilities over visible bits are interested
- The hidden bits are the latent representation learned by the network

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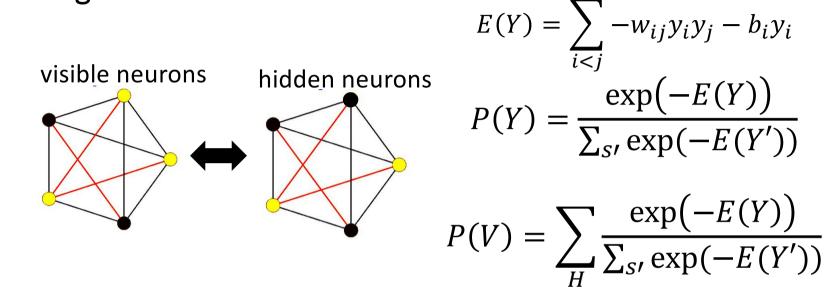
$$P(Y) = \frac{\exp(-E(Y))}{\sum_{s'} \exp(-E(Y'))}$$

$$P(Y) = P(V, H)$$

$$P(V) = \sum_{H} P(Y)$$
Maximise this term for training patterns

- Y=(V, H)
 - V: output of the visible neurons
 - H: output of the hidden neurons
- The marginal probabilities over visible bits are interested
- The hidden bits are the latent representation learned by the network





- Train the network to assign a desired probability distribution to the visible states
- Probability of visible state sums over all hidden states



$$\log(P(V)) = \log\left(\sum_{H} \exp\left(\sum_{i < j} w_{ij} y_i y_j\right)\right) - \log\left(\sum_{Y'} \exp\left(\sum_{i < j} w_{ij} y_i' y_j'\right)\right)$$
$$\mathcal{L} = \frac{1}{N} \sum_{V \in \{V\}} \log(P(V))$$
$$= \frac{1}{N} \sum_{V \in \{V\}} \log\left(\sum_{H} \exp\left(\sum_{i < j} w_{ij} y_i y_j\right)\right) - \log\left(\sum_{Y'} \exp\left(\sum_{i < j} w_{ij} y_i' y_j'\right)\right)$$

- The loss function is average log likelihood of visible neurons of training vectors {V}= {V₁, V₂, ..., V_N}
 - should be maximised
 - Two terms have the same format



$$\mathcal{L} = \frac{1}{N} \sum_{V \in \{V\}} \log\left(\sum_{H} \exp\left(\sum_{i < j} w_{ij} y_i y_j\right)\right) - \log\left(\sum_{Y'} \exp\left(\sum_{i < j} w_{ij} y'_i y'_j\right)\right)$$
$$\frac{d\mathcal{L}}{dw_{ij}} = \frac{1}{N} \sum_{V \in \{V\}} \sum_{H} P(Y|V) y_i y_j - \sum_{Y'} P(Y') y'_i y'_j$$

- Similar as the setting without hidden neurons
- But both terms are summations over an exponential states
 - Both need sampling



$$\frac{d\mathcal{L}}{dw_{ij}} = \frac{1}{N} \sum_{V \in \{V\}} \sum_{H} P(Y|V)y_iy_j - \sum_{Y'} P(Y')y'_iy'_j$$
$$\sum_{H} P(Y|V)y_iy_j = \frac{1}{K} \sum_{H \in H_{samples}} y_iy_j$$
$$\sum_{Y'} P(Y')y'_iy'_j = \frac{1}{M} \sum_{Y' \in S_{samples}} y'_iy'_j$$

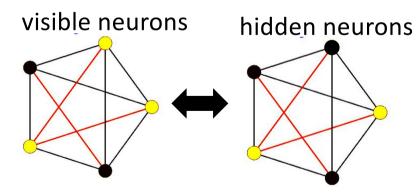
- The first term is calculated as the average of sampled hidden state with the visible state fixed
- The second term is calculated as the average of sampled states "freely"



Training Process–Sample 1

- For each training pattern V_i :
 - Fix visible neurons according to V_i
 - Let the hidden neurons evolve from a random initial point to generate H_i
 - Get $Y_i = [V_i, H_i]$
- Repeat K times to generate synthetic training

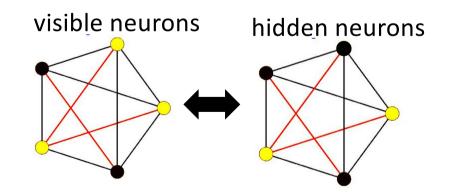
•
$$Y = \{Y_{1,1}, Y_{1,2}, \dots, Y_{1,K}, Y_{2,1}, \dots, Y_{N,K}\}$$





Training Process – Sample 2

- Unclamp the visible units and let the entire network evolve several times to generate
 - $Y_{samples} = \{Y_{sample,1}, Y_{sample,2}, \dots, Y_{sample,M}\}$

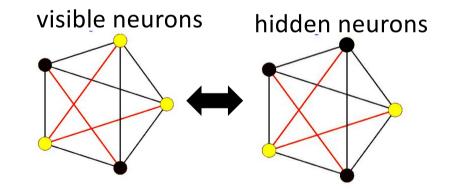




Training Process

$$\frac{d\mathcal{L}}{dw_{ij}} = \frac{1}{NK} \sum_{Y} y_i y_j - \frac{1}{M} \sum_{Y' \in Y_{sample}} y'_i y'_j$$
$$w_{ij} = w_{ij} + \alpha \frac{d\mathcal{L}}{dw_{ij}}$$

- Initialise weights
- Get training samples
- Compute gradient and update weights
- Iterate until convergence





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Boltzmann Machine

- Stochastic extension of Hopfield network
- Store more patterns than Hopfield network through hidden neurons
- Application:
 - Pattern completion
 - Pattern denoising
 - Computing conditional probabilities of patterns
 - Classification
 - Add more bits representing class
 - $[y_1, ..., y_N, class]$



Boltzmann Machine

- Training process takes a long time...
- Can't work for large problems
- How to solve these problems?



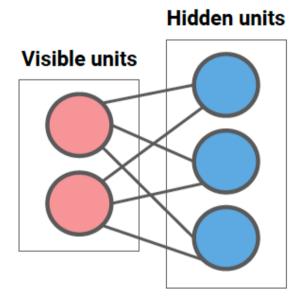
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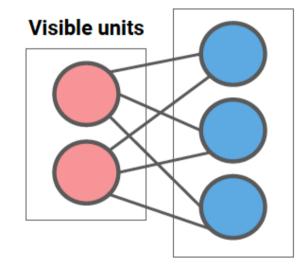
- Restricted
 - There are no visible-visible and hidden-hidden connections.
 - Proposed as "Harmonium Models" by Paul Smolensky
- Joint Distribution:

•
$$P(V,H) = \frac{\exp(V^T W H + bV + cH)}{\sum_{v'h'} \exp(V'^T W H' + bV' + cH')}$$





Hidden units



- Pros:
 - Sample for hidden neurons: no looping

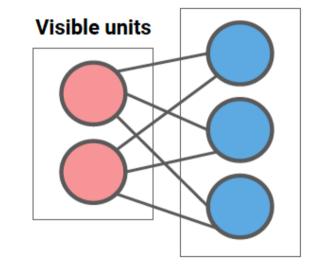
Hidden: $z_i = \sum_j w_{ji} v_i + b_i$ $P(h_i = 1) = \frac{1}{1 + e^{-z_i}}$

Visible: $y_i = \sum_j w_{ji}h_i + b_i$ $P(v_i = 1) = \frac{1}{1 + e^{-y_i}}$

• Sample for all neurons: bigraph



Hidden units



- For each sample:
 - Initialize visible neurons
 - Iteratively generate hidden and visible units

Hidden: $z_i = \sum_j w_{ji} v_i + b_i$ $P(h_i = 1) = \frac{1}{1 + e^{-z_i}}$

Visible: $y_i = \sum_j w_{ji} h_i + b_i$ $P(v_i = 1) = \frac{1}{1 + e^{-y_i}}$

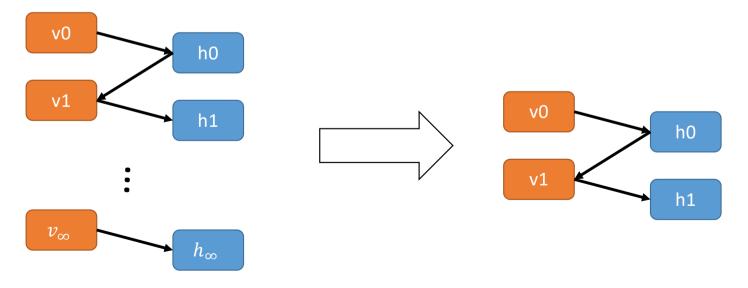
• $\frac{d\log p}{dw_{ij}} = \langle v, h \rangle^0 - \langle v, h \rangle^\infty$



Contrastive Divergence

- Recall in Hopfield Network:
 - No need to raise the entire surface, just the neighborhood
- One iteration is enough in RBM

•
$$\frac{d \log p}{d w_{ij}} = \langle v, h \rangle^0 - \langle v, h \rangle^1$$

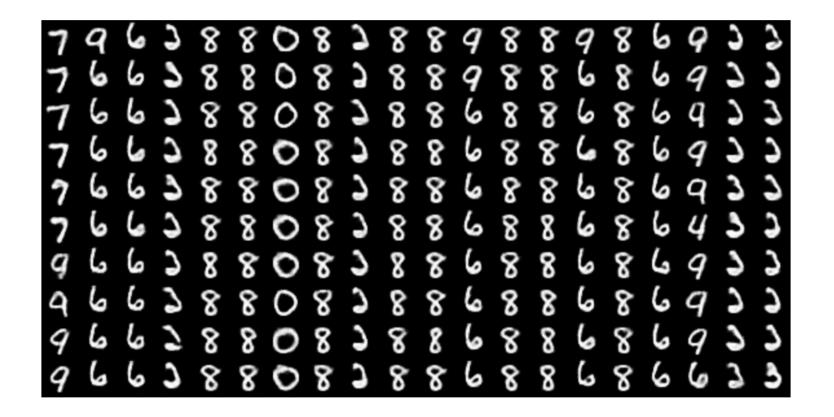




- Generative models for binary data
- Can be extended to continuous-valued data
 - Change the distribution of visible neurons (or hidden neurons)
 - "Exponential Family Harmoniums with an Application to Information Retrieval", Welling et al., 2004
- Useful for classification and regression



Boltzmann Machines: samples





Content

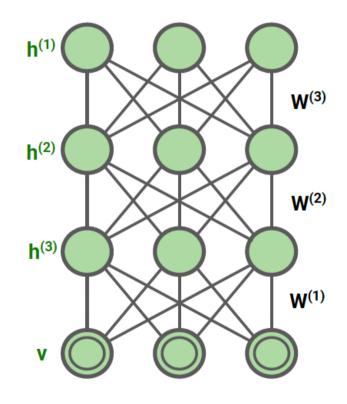
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Deep Boltzmann Machines

- Stacked RBMs are one of the first deep generative models
- Bottom layer v are visible neurons
- Multiple hidden layers



Deep Boltzmann machine



Boltzmann Machines: samples



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Training samples

Generated samples 论 r 60



Reference

- CMU 11-785 Lec 19
- Stanford cs236 Lec 11



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 DBM



Thanks