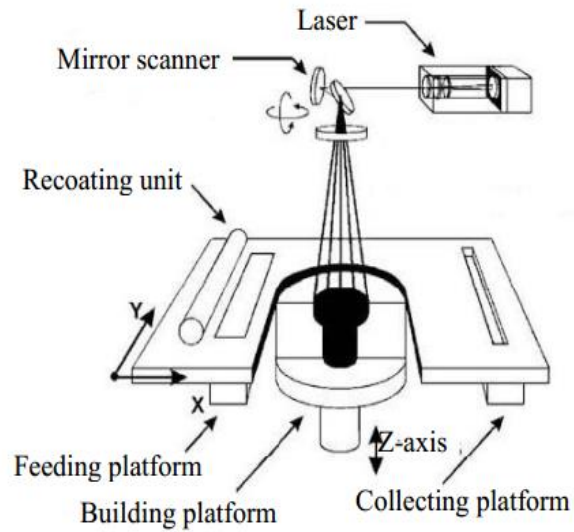


# **Application CGAN on Addictive Manufacturing**

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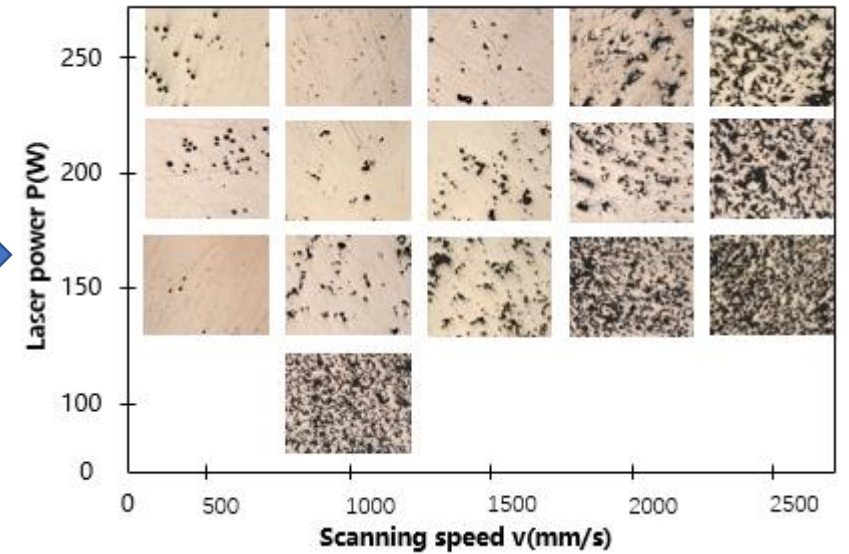
# Introduction



SLM

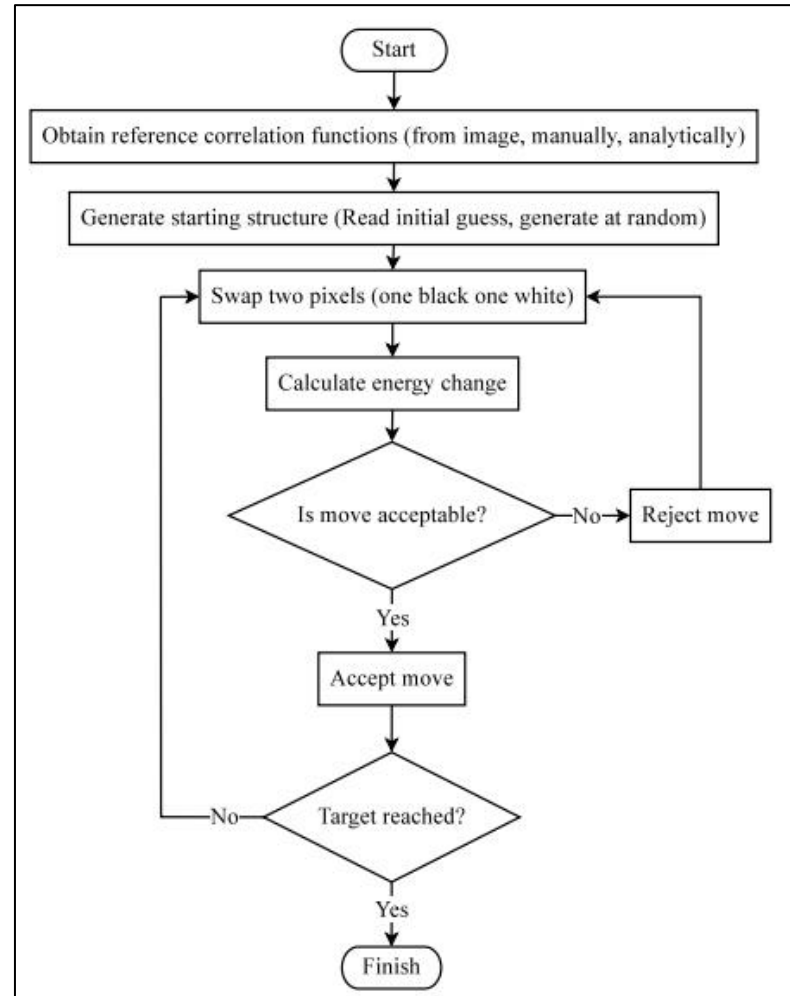
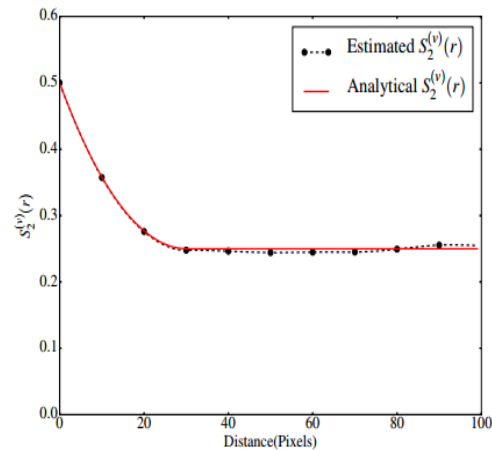


Samples



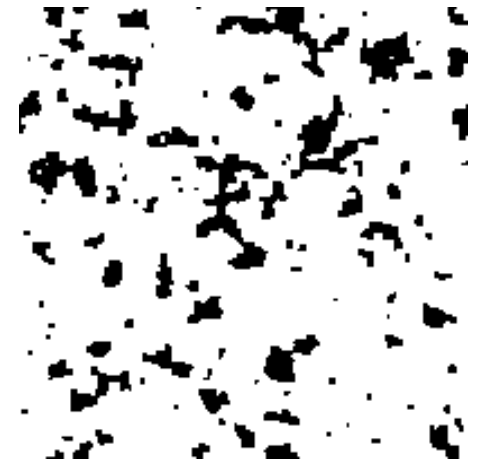
Microstructure

# Related Work



$$E_t = \sum_k [f_t - f_0]^{2\epsilon}$$

$$p(\Delta E_t) = \begin{cases} 1, \Delta E_t \leq 0 \\ \exp\left(-\frac{\Delta E_t}{T_t}\right), \Delta E_t > 0 \end{cases}$$



Size:200\*200

Reconstruction time: 3h

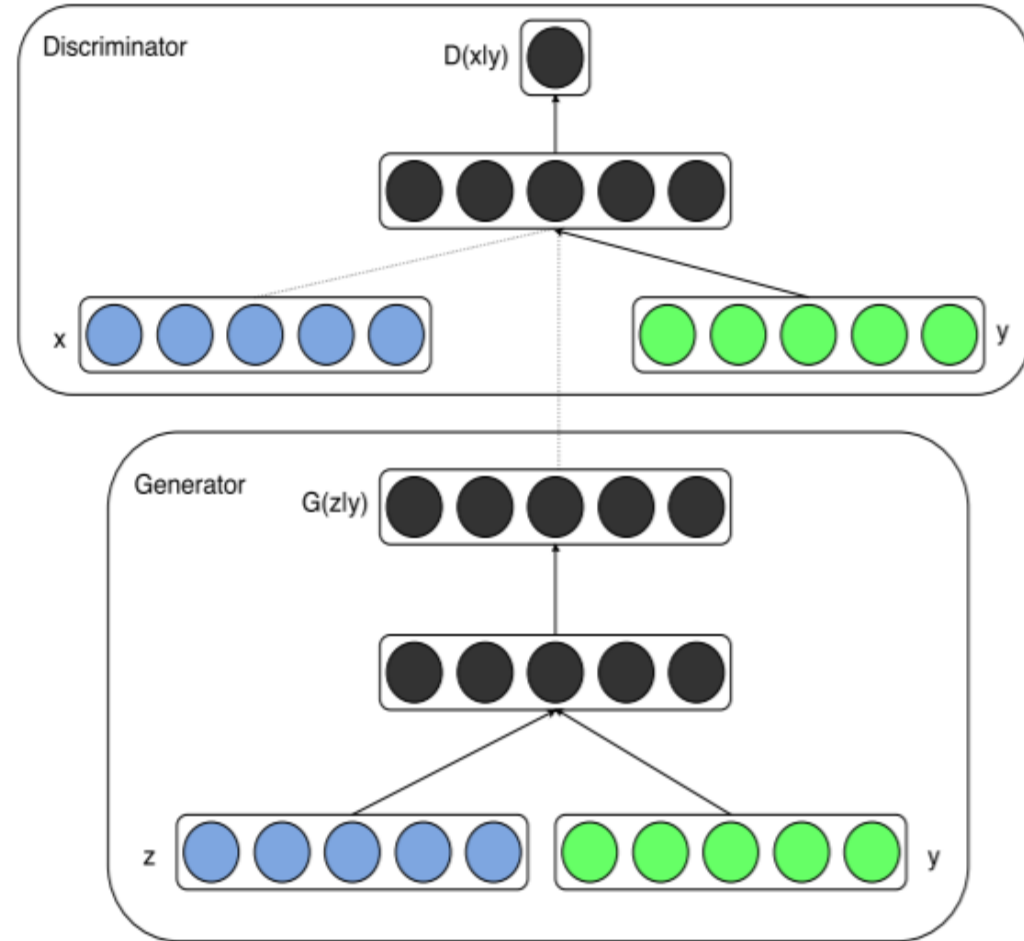
# Method

$x$ : microstructure  
 $y$ : processing parameters  
 $z$ : a noise prior

Processing parameters:

| Power(W) | Speed(mm/s) |     |      |  |
|----------|-------------|-----|------|--|
| 100      | 800         | 300 | 1300 |  |
| 200      | 300         | 300 | 2000 |  |
| 200      | 800         | 300 | 3000 |  |
| 200      | 1300        | 400 | 300  |  |
| 200      | 2000        | 400 | 800  |  |
| 200      | 3000        | 400 | 1300 |  |
| 300      | 300         | 400 | 2000 |  |
| 300      | 800         | 400 | 3000 |  |

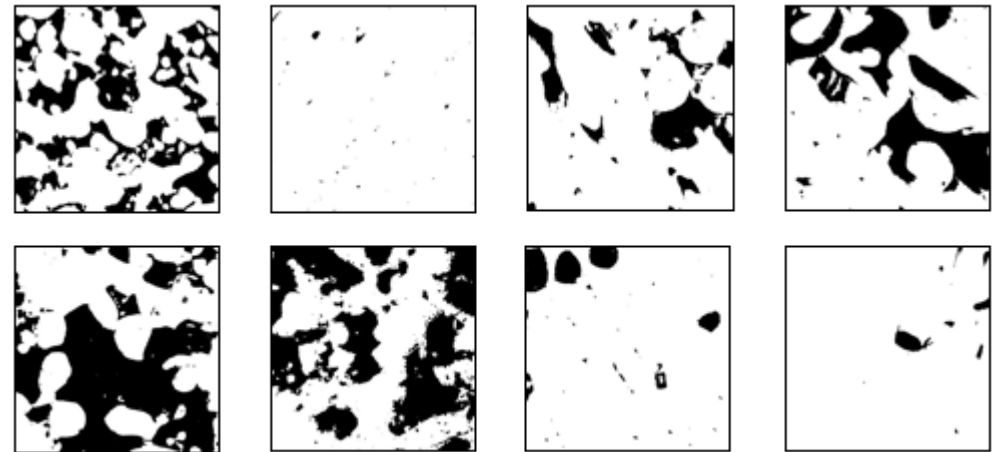
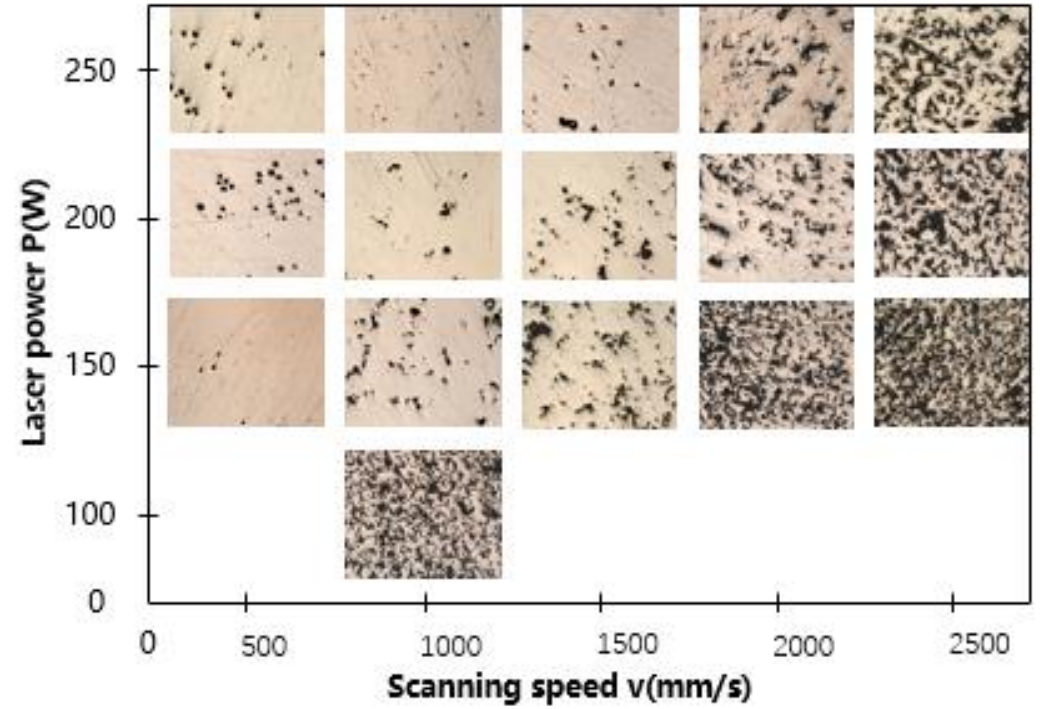
Our goal:  $G(X|Z,Y,\theta)$



# Method

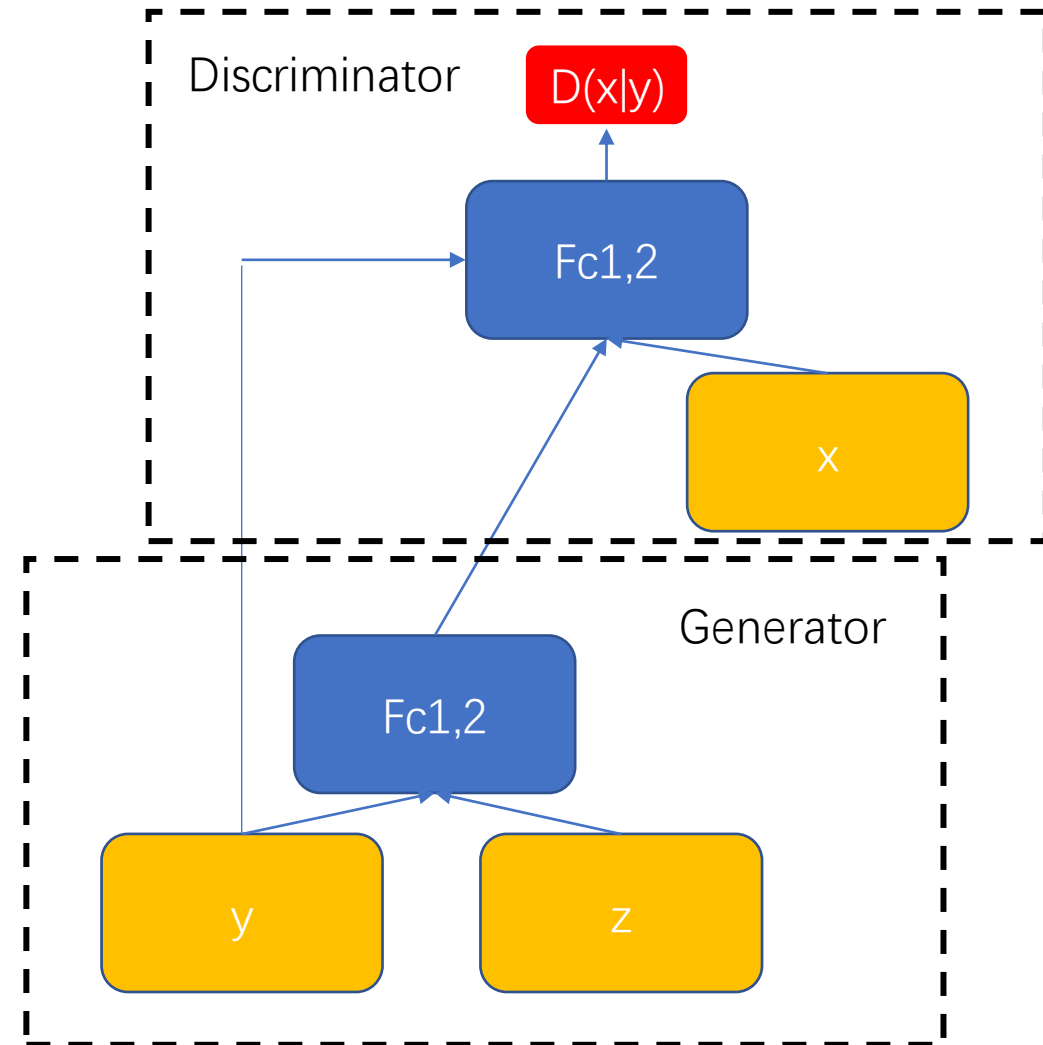
Original: 16\*16  
Image size: 2752\* 2208

Preprocessing:  
16\*16  
Image size: 20\*550\*550



# Method

$x$ : microstructure  
 $y$ : processing parameters  
 $z$ : a noise prior



# Method

Model structure:

```
generator(  
  (fc1_1): Linear(in_features=100, out_features=256, bias=True)  
  (fc1_1_bn): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
  (fc1_2): Linear(in_features=2, out_features=256, bias=True)  
  (fc1_2_bn): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
  (fc2): Linear(in_features=512, out_features=512, bias=True)  
  (fc2_bn): BatchNorm1d(512, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
  (fc3): Linear(in_features=512, out_features=2048, bias=True)  
  (fc3_bn): BatchNorm1d(2048, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
  (fc4): Linear(in_features=2048, out_features=40000, bias=True)  
)
```

Optimizer:

```
# Adam optimizer  
G_optimizer = optim.Adam(G.parameters(), lr=lr, betas=(0.5, 0.999))  
D_optimizer = optim.Adam(D.parameters(), lr=lr, betas=(0.5, 0.999))
```

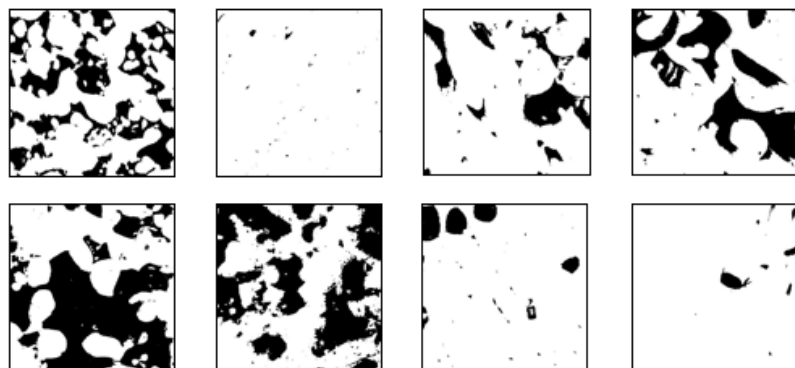
In [459]: D

Out[459]:

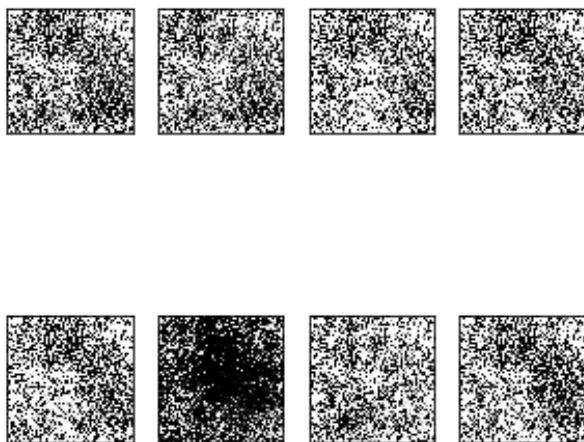
```
discriminator(  
  (fc1_1): Linear(in_features=40000, out_features=1024, bias=True)  
  (fc1_2): Linear(in_features=2, out_features=1024, bias=True)  
  (fc2): Linear(in_features=2048, out_features=512, bias=True)  
  (fc2_bn): BatchNorm1d(512, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
  (fc3): Linear(in_features=512, out_features=256, bias=True)  
  (fc3_bn): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
  (fc4): Linear(in_features=256, out_features=1, bias=True)  
)
```

# Evaluation

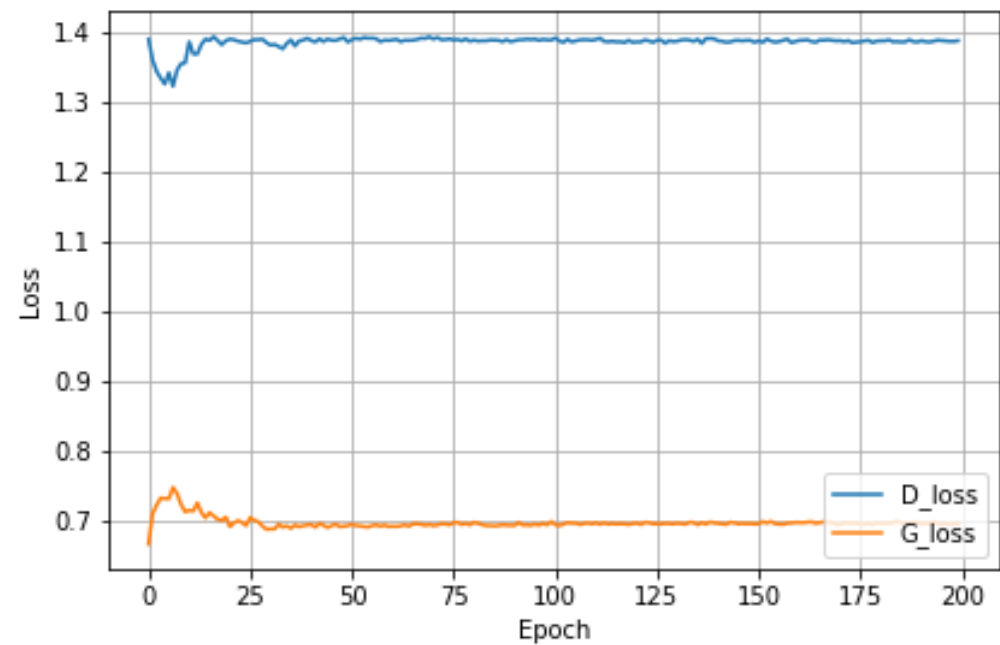
Original:



Reconstruction:



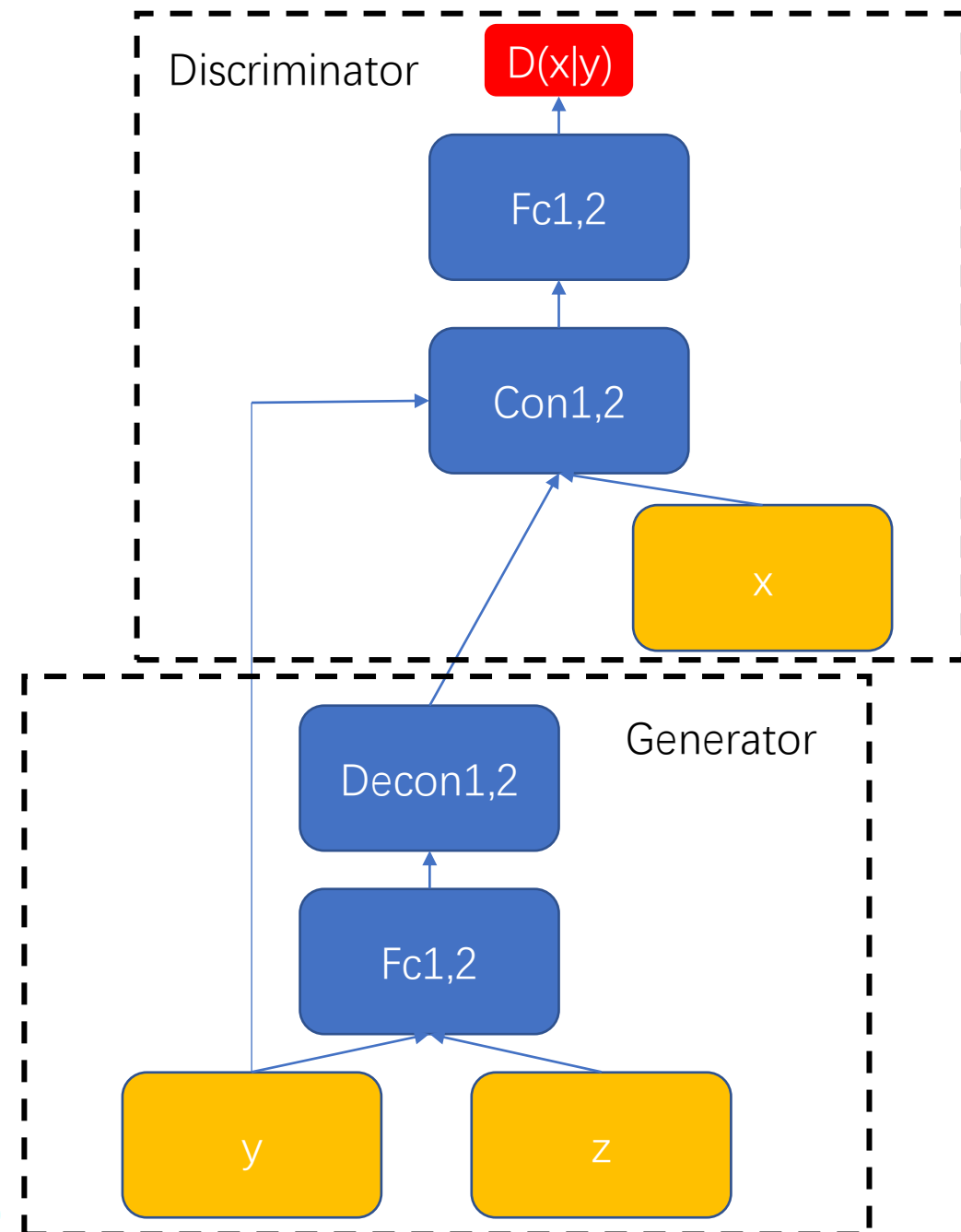
Loss:





# Method

$x$ : microstructure  
 $y$ : processing parameters  
 $z$ : a noise prior



```
# Adam optimizer
```

```
G_optimizer = optim.Adam(G.parameters(), lr=lr, betas=(0.5, 0.999))  
D_optimizer = optim.Adam(D.parameters(), lr=lr, betas=(0.5, 0.999))
```

# Method

Model structure:

```
generator(  
  (fc): Sequential(  
    (0): Linear(in_features=102, out_features=1024, bias=True)  
    (1): BatchNorm1d(1024, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
    (2): ReLU()  
    (3): Linear(in_features=1024, out_features=320000, bias=True)  
    (4): BatchNorm1d(320000, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
    (5): ReLU()  
  )  
  (deconv): Sequential(  
    (0): ConvTranspose2d(128, 64, kernel_size=(4, 4), stride=(2, 2),  
    (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_  
    (2): ReLU()  
    (3): ConvTranspose2d(64, 1, kernel_size=(4, 4), stride=(2, 2), pa  
    (4): Tanh()  
  )  
)
```

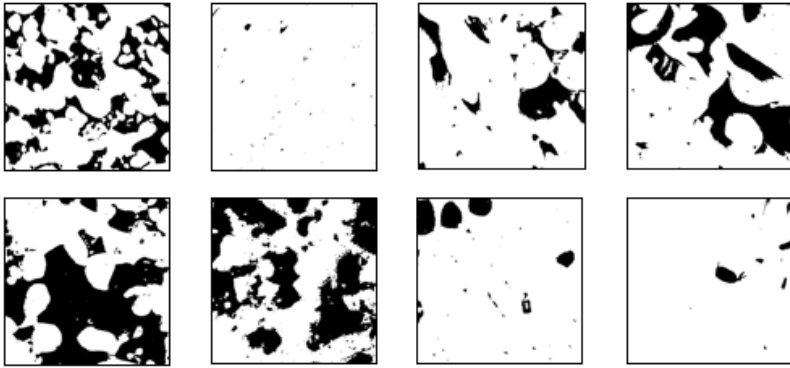
```
Out[456]:  
discriminator(  
  (conv): Sequential(  
    (0): Conv2d(3, 64, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1))  
    (1): LeakyReLU(negative_slope=0.2)  
    (2): Conv2d(64, 128, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1))  
    (3): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_  
    (4): LeakyReLU(negative_slope=0.2)  
  )  
  (fc): Sequential(  
    (0): Linear(in_features=320000, out_features=1024, bias=True)  
    (1): BatchNorm1d(1024, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True)  
    (2): LeakyReLU(negative_slope=0.2)  
    (3): Linear(in_features=1024, out_features=1, bias=True)  
    (4): Sigmoid()  
  )  
)
```

Optimizer:

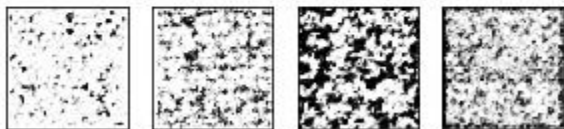
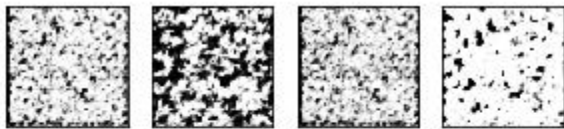
```
# Adam optimizer  
G_optimizer = optim.Adam(G.parameters(), lr=lr, betas=(0.5, 0.999))  
D_optimizer = optim.Adam(D.parameters(), lr=lr, betas=(0.5, 0.999))
```

# Evaluation

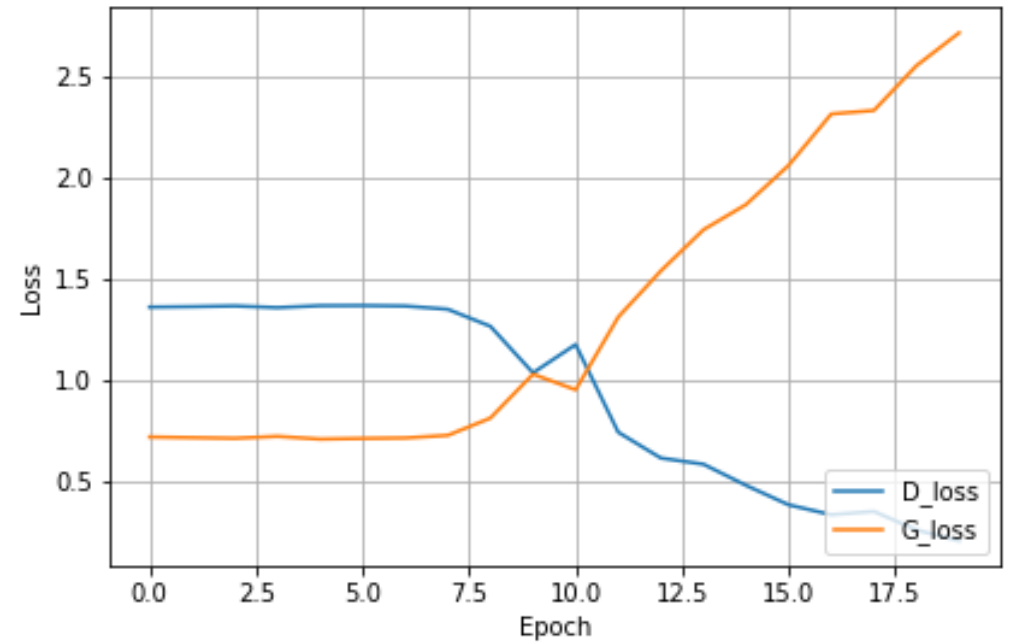
Original:



Reconstruction:



Loss:



**Any suggestion?**